

# WORKSHOP

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Measurement of luminance distributions in the field of view  
for glare evaluations

## HDR Cameras

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# Glare and luminance

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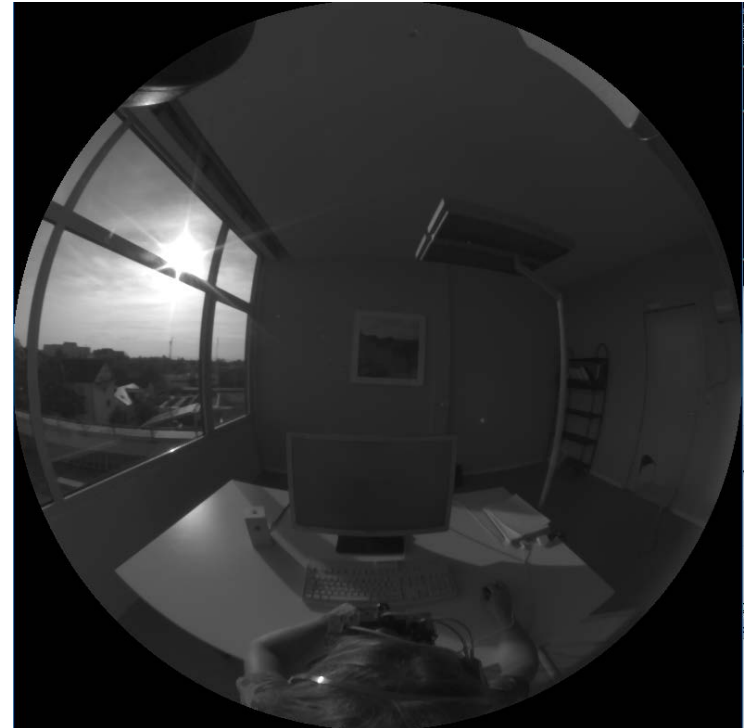
Reliable glare studies



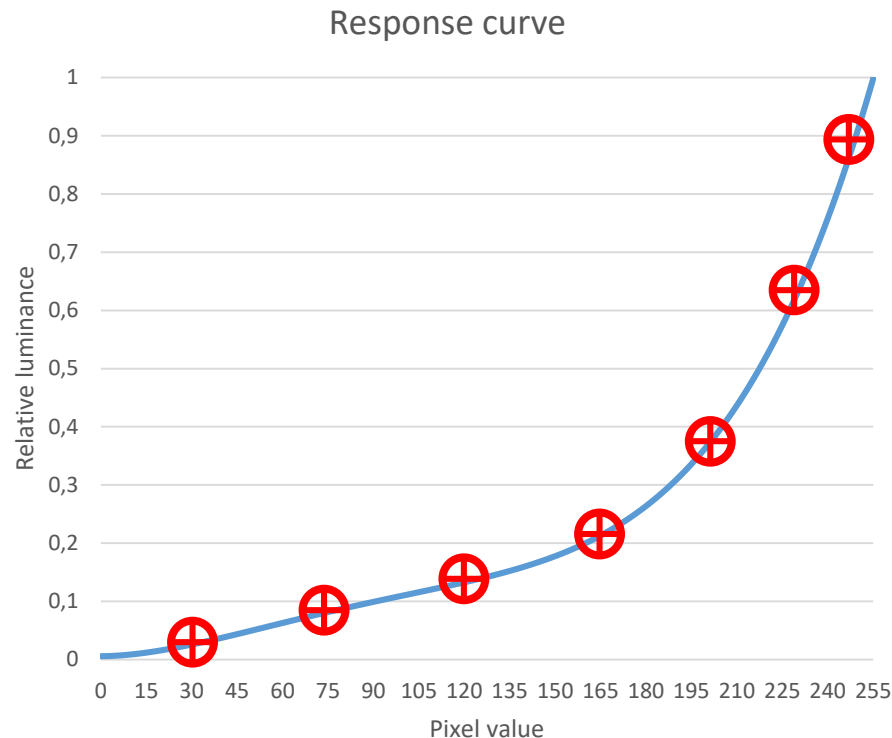
Reliable luminance measurements

2 different methods

- Absolute calibration
- "Self-calibration"
  - Automatic algorithm



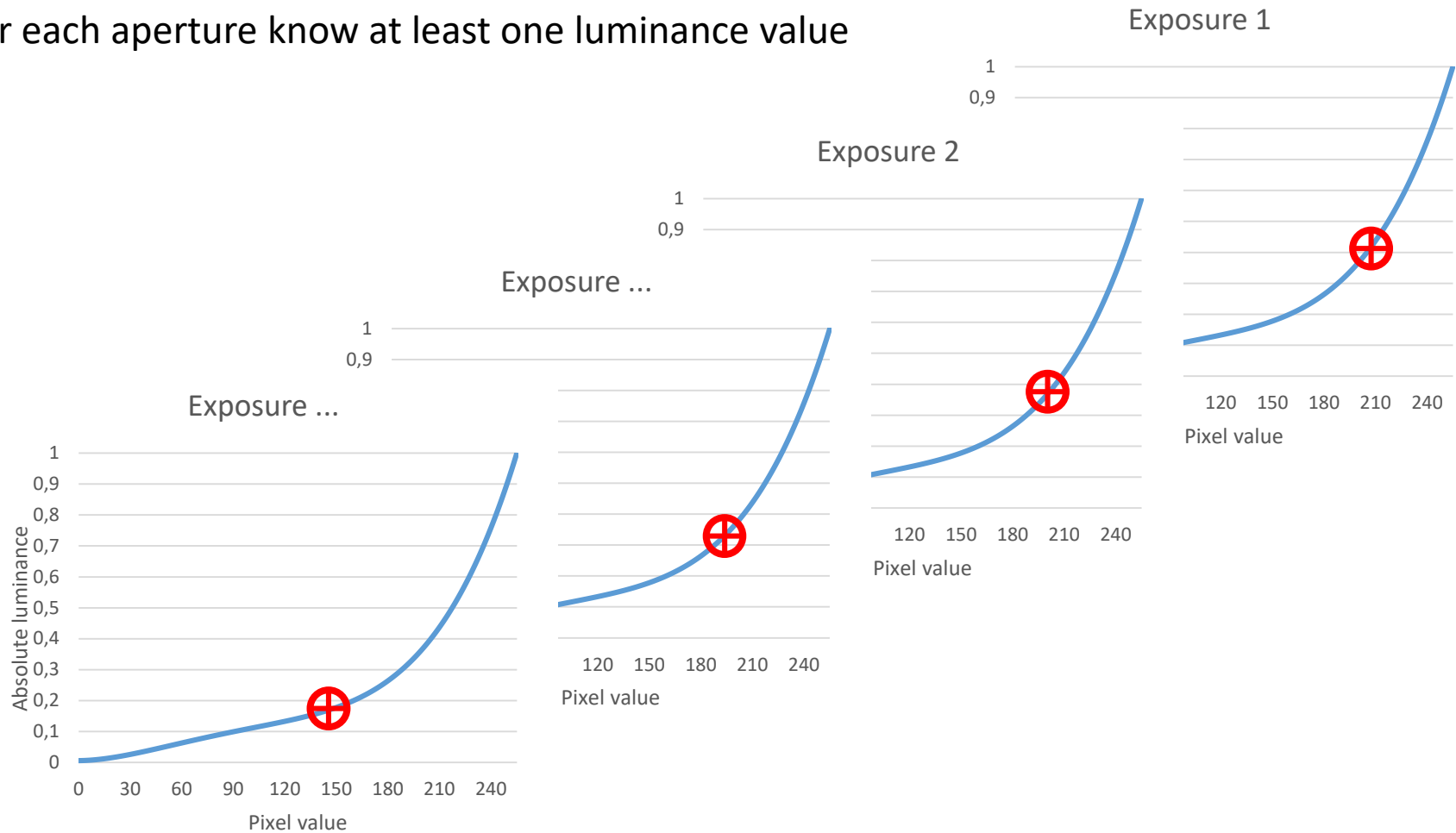
# Absolute HDR camera calibration



The shape of the response curve

# Absolute HDR camera calibration

For each aperture know at least one luminance value



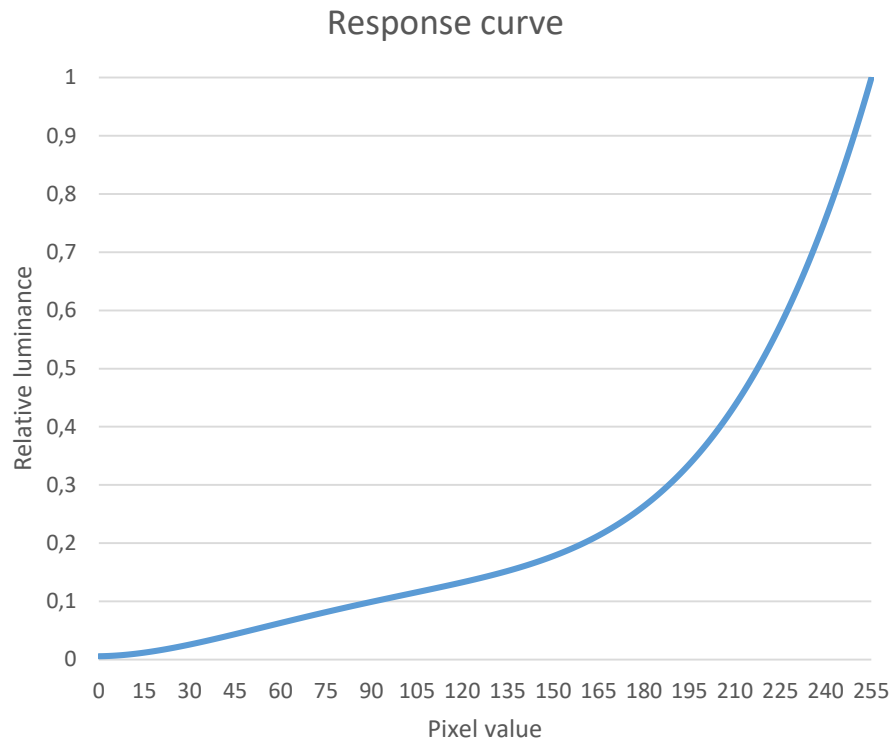
# HDR generation

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Luminance values calculated based on pixel value,  
response curve and exposure

# Automatic algorithm HDR camera calibration

An automatic calibration algorithm is used to derive a response curve



$$20 < \textit{Pixel Value} < 200$$

# Automatic algorithm HDR camera calibration

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## Different programs

- PFSTools
- hdrngen
  - Photosphere
  - WebHDR

Use up-to-date versions – also of Radiance (current version 5.1)

# DSLR camera “self/calibration” procedure

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Create LDR images

Create HDR image

Cut images

Calibrate for vignetting

Calibrate for projection

Luminance calibration

Illuminance check



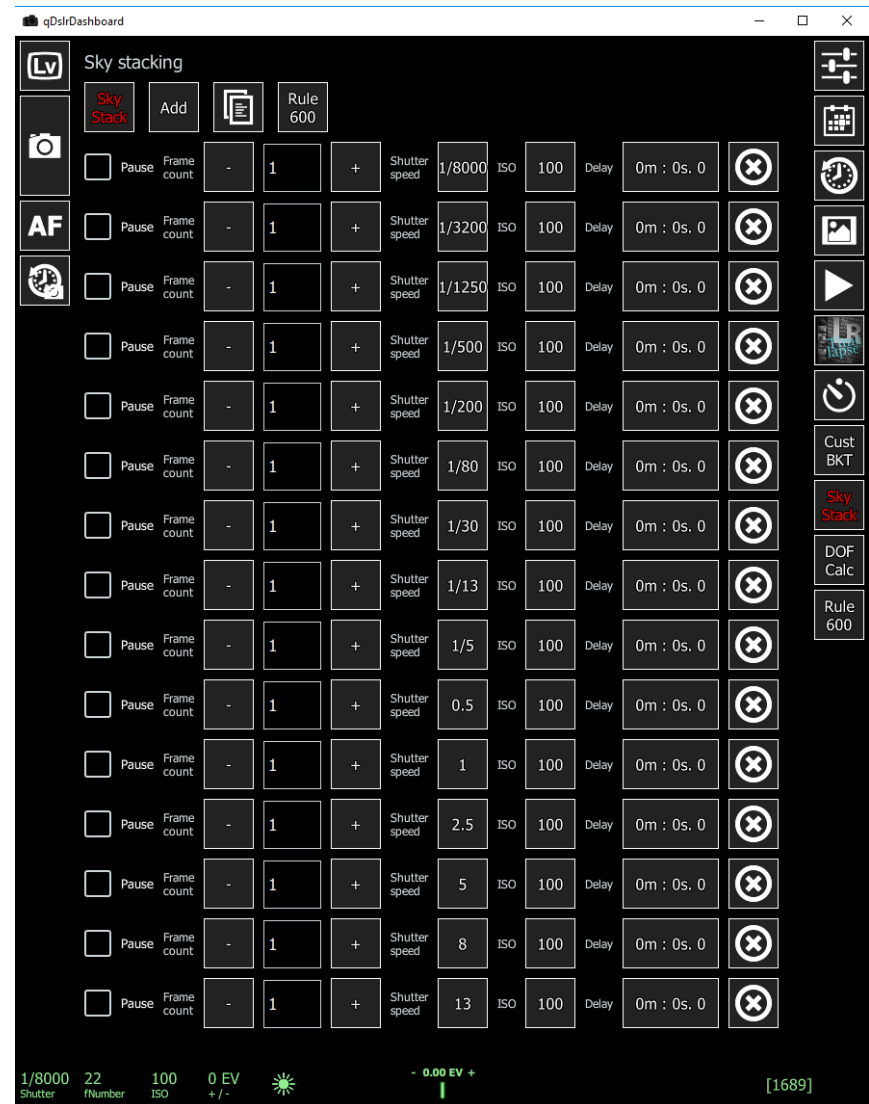
## General camera settings

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ISO speed	100
White balance	Daylight
Image quality	.JPEG (large)
Color space	sRGB
Focus	Infinity (auto off)
Picture style	Standard

## General camera setup

- Auto bracketing
- Computer control
  - Manufactures
  - qDSLRdashboard



## General camera setup



1 EV stop between images

## General camera setup

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- Avoid movement in scene (avoid ghosting)
- Avoid shaking camera
- Use a tripod
- Use a computer for bracketing
- Black to white image series
- Use targets in the scene
  - High luminance
  - Low luminance
- Measure vertical illuminance



# DSLR camera “self/calibration” procedure

---

Create LDR images

Create HDR image

Cut images

Calibrate for vignetting

Calibrate for projection

Luminance calibration

Illuminance check

# HDR generation

---

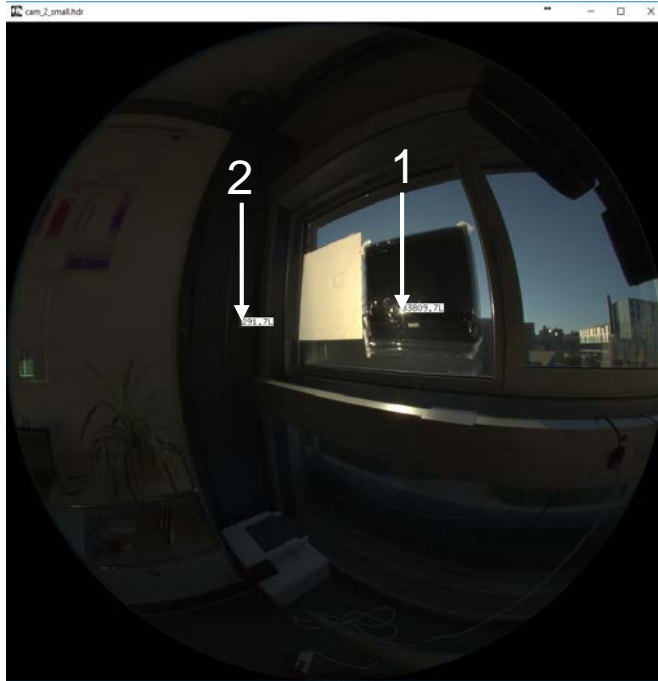
## Generate HDR

`hgrgen -o -r -a -e -f -g -x`

- o = output file
- r = response curve file
- a = automatic exposure alignment
- e = exposure adjustment
- f = flare removal
- g = ghost removal
- ~~x = over and under exposure removal~~

# HDR generation

With  $-x$  option



1: 89.809  $\text{cd/m}^2$   
2: 291  $\text{cd/m}^2$

Without  $-x$  option



1: 2.653.980  $\text{cd/m}^2$   
2: 281  $\text{cd/m}^2$

Konica Minolta: 1: 1.674.000  $\text{cd/m}^2$   
2: 275  $\text{cd/m}^2$



# HDR generation

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## Check LDR images

- Darkest should not have pixels  $> 200$
- Whitest should not have pixels  $< 20$

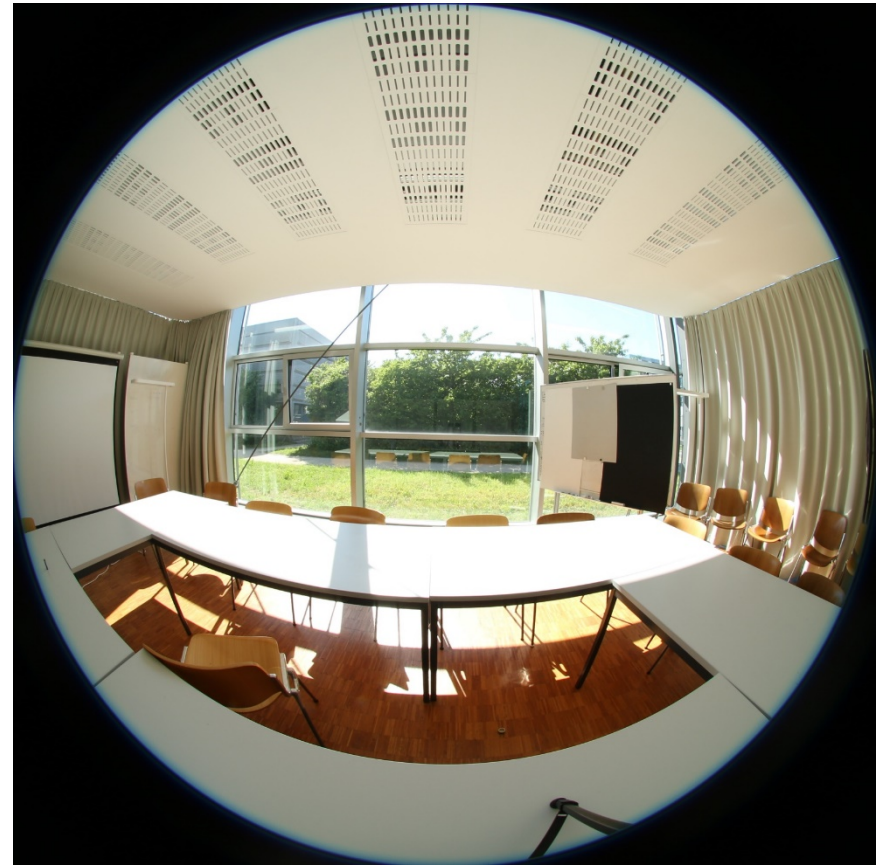


## Response curve

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Scene should contain

- bright areas
- dark areas
- white and/or grey areas



## Response curve – HDR generation

`hgrgen -o -r -a -e -f -g`  to generate HDR and curve

With `-r` option give name to response curve file

Save it and use it to make HDR images

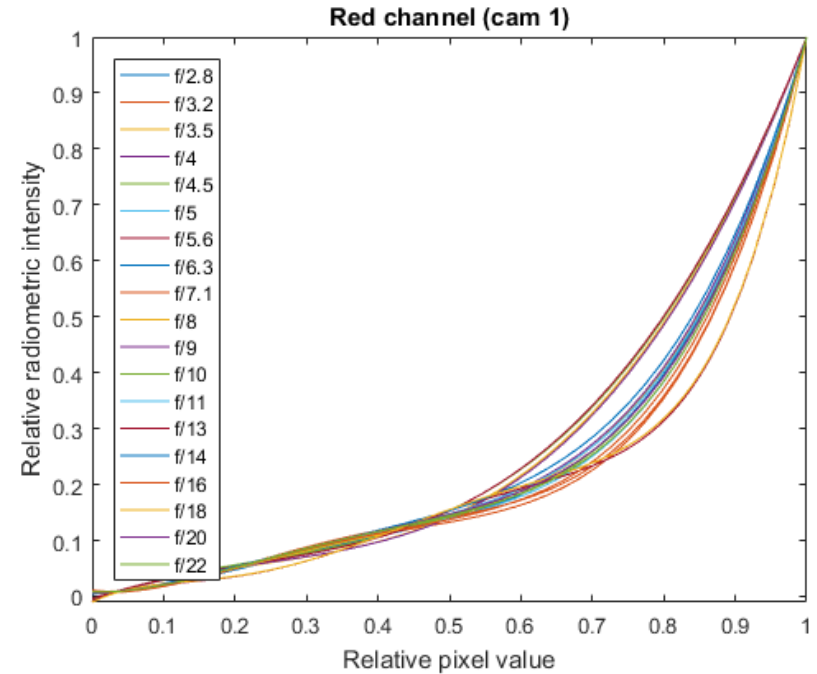
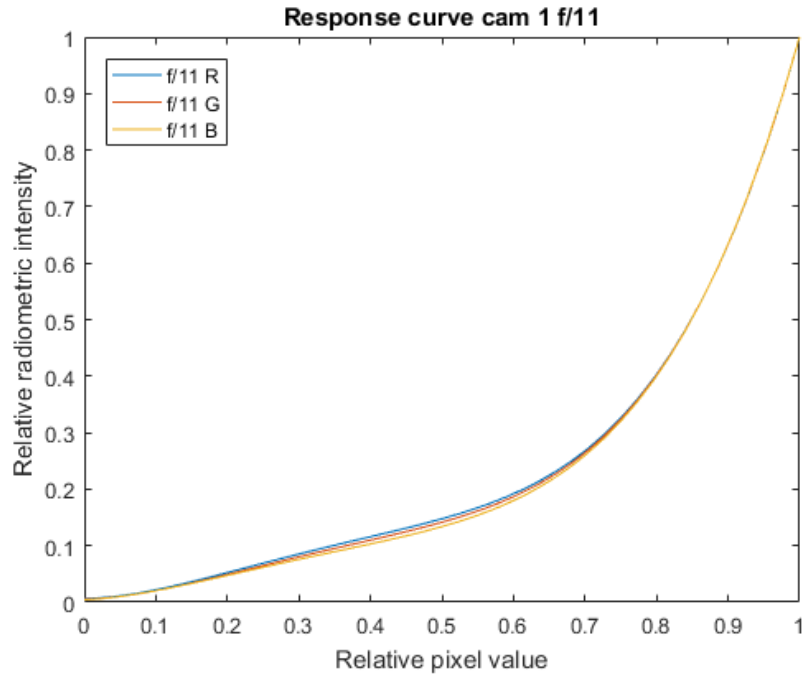
 `/home/phansen/Camera_calibration/Response_curve/Response_cam_1/11/11.rsp`



```
4 3.33299 -4.10854 1.75235 0.0167096 0.00648387
4 3.2037 -3.86379 1.63398 0.0207269 0.00537953
4 2.96702 -3.38244 1.35453 0.0567263 0.00416186
```

 `[n]` degree polynomial

# Response curve



Differs for all cameras and apertures

# DSLR camera “self/calibration” procedure

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Create LDR images

Create HDR image

Cut images

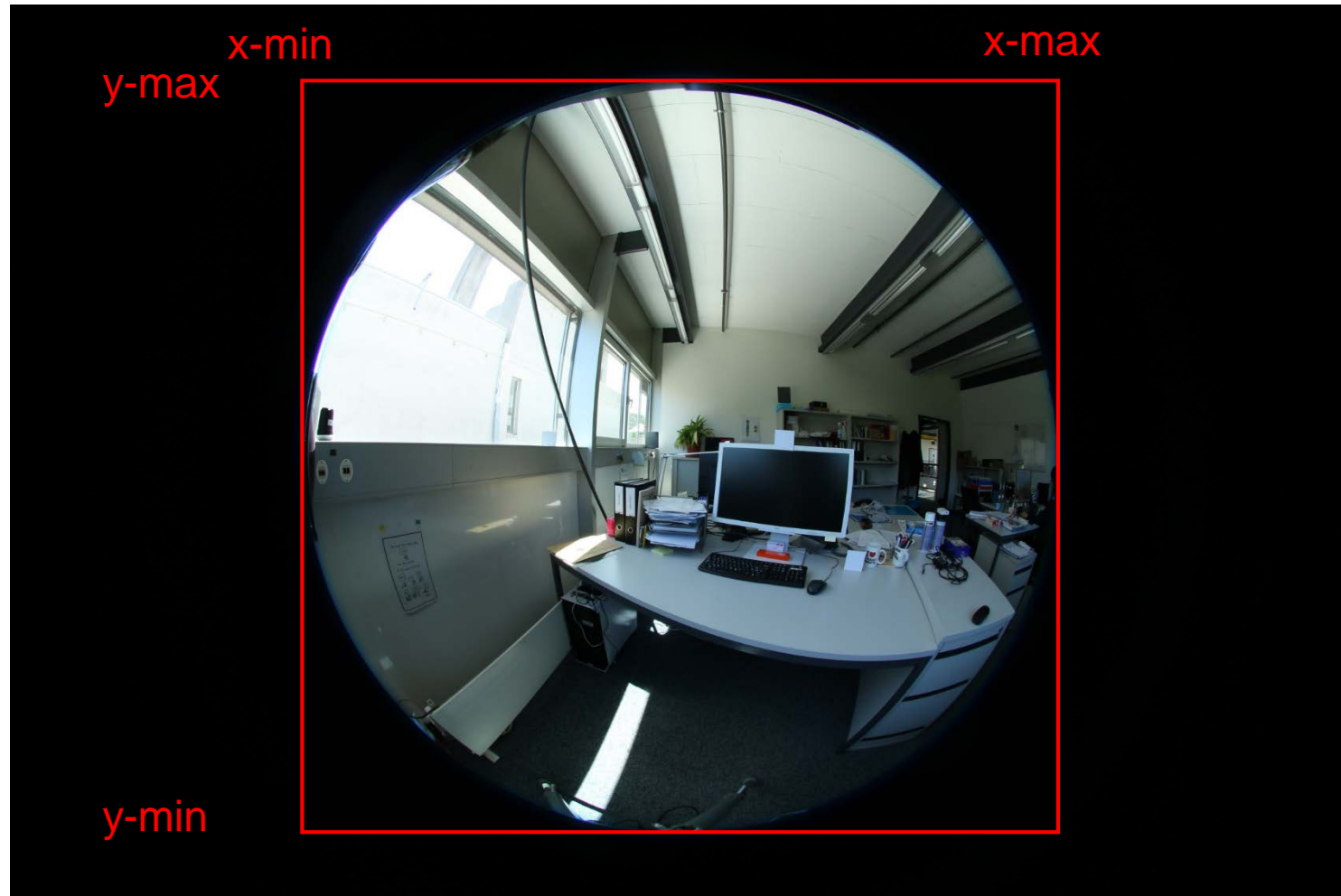
Calibrate for vignetting

Calibrate for projection

Luminance calibration

Illuminance check

## Cut HDR image



`pcompos -x [x-max] -y [y-max] -h [org_image.hdr] -[x-min] -[y-min] > [cut_image.hdr]`

# DSLR camera “self/calibration” procedure

---

Create LDR images

Create HDR image

Cut images

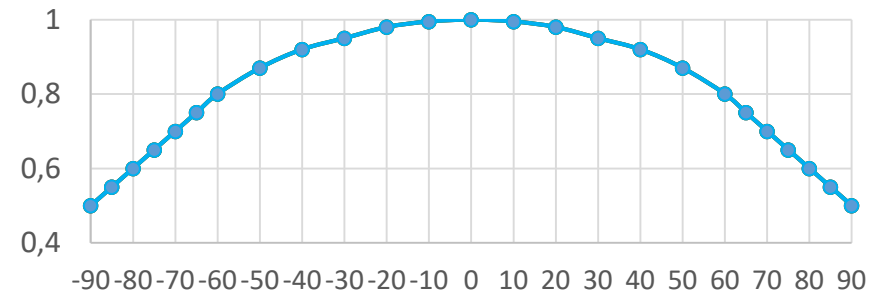
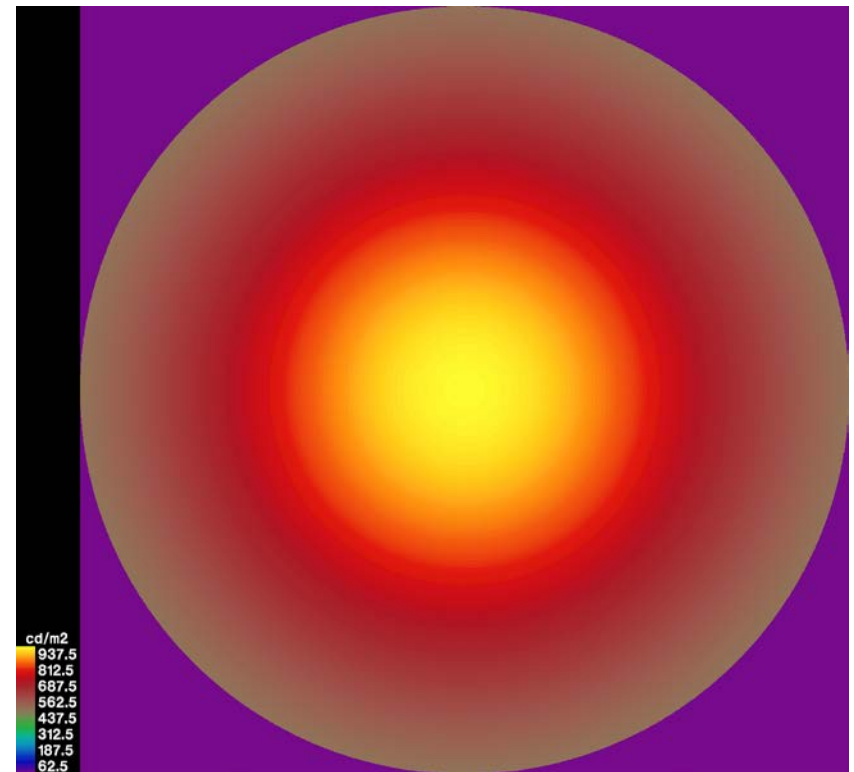
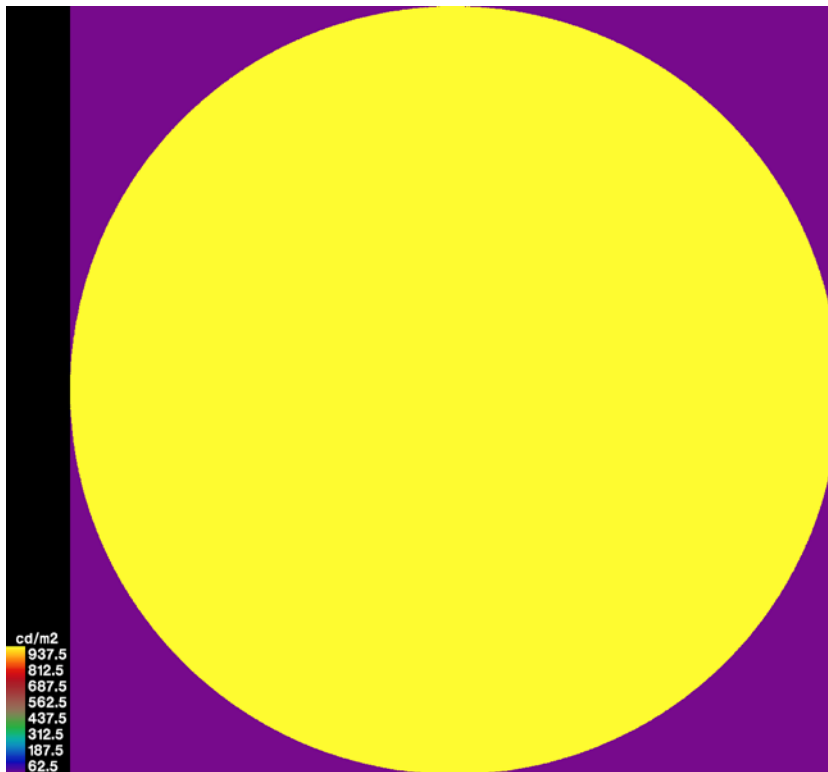
Calibrate for vignetting

Calibrate for projection

Luminance calibration

Illuminance check

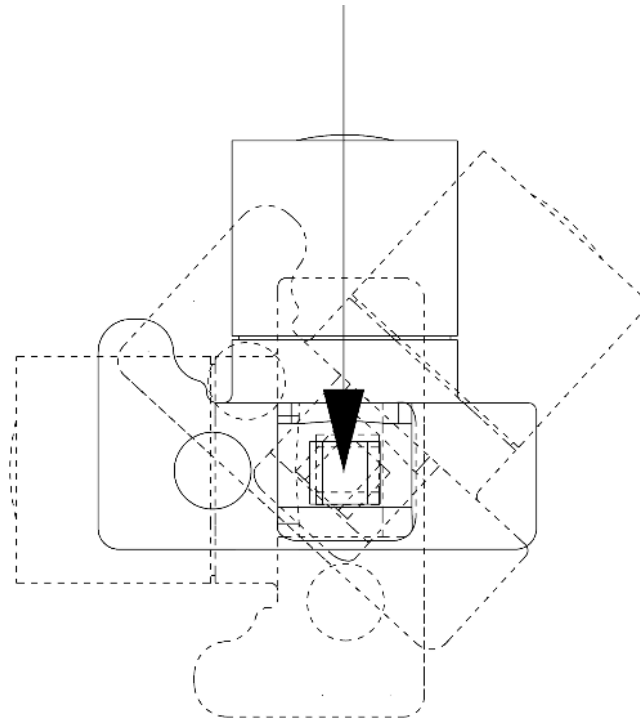
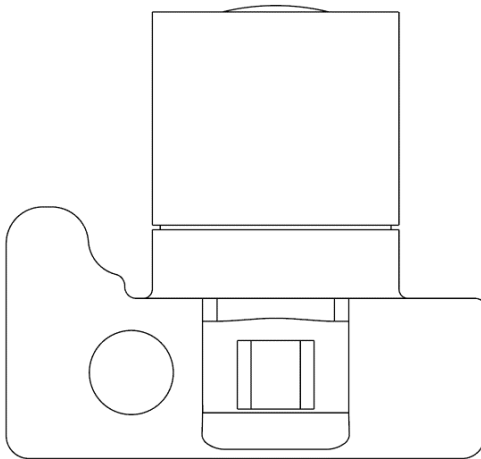
# Vignetting



# Vignetting



Normal camera rotation point

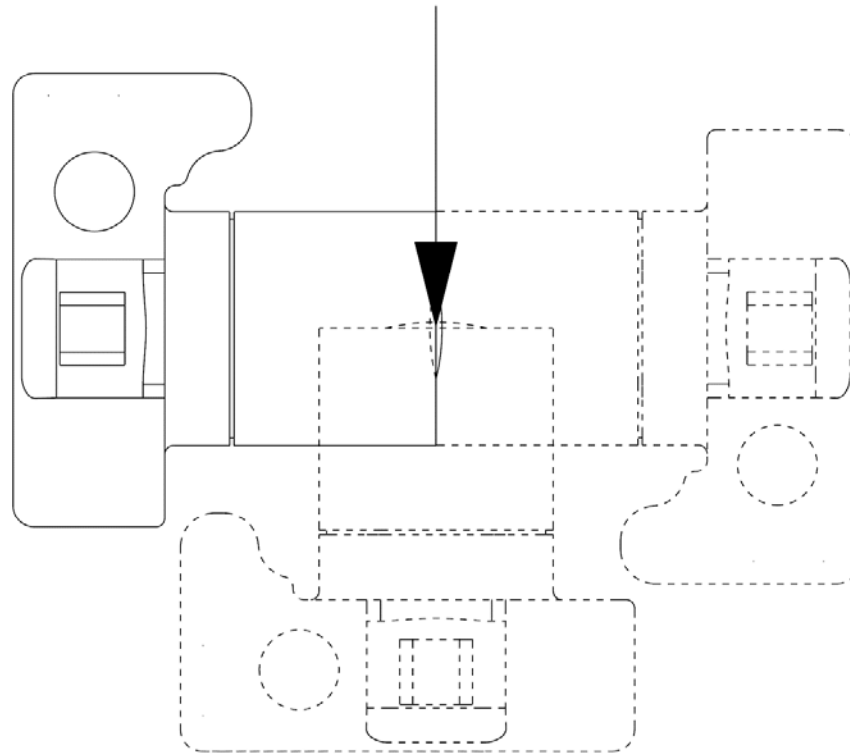




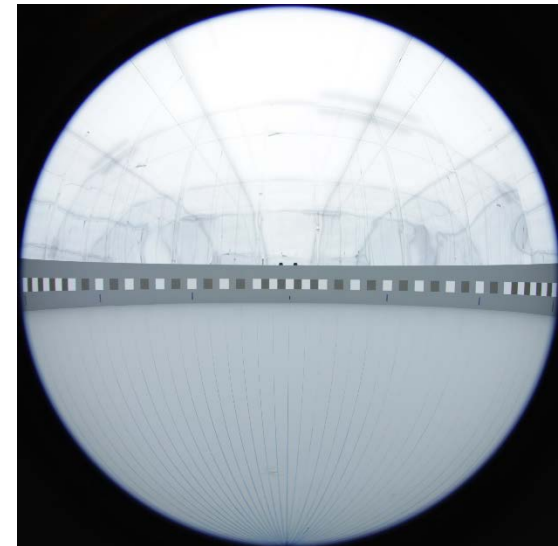
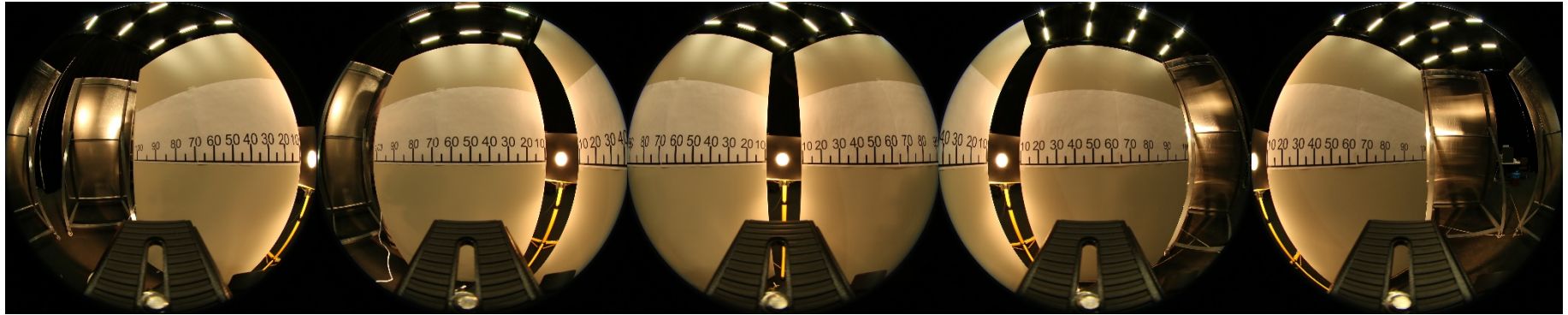
# Vignetting



Nodal rotation point

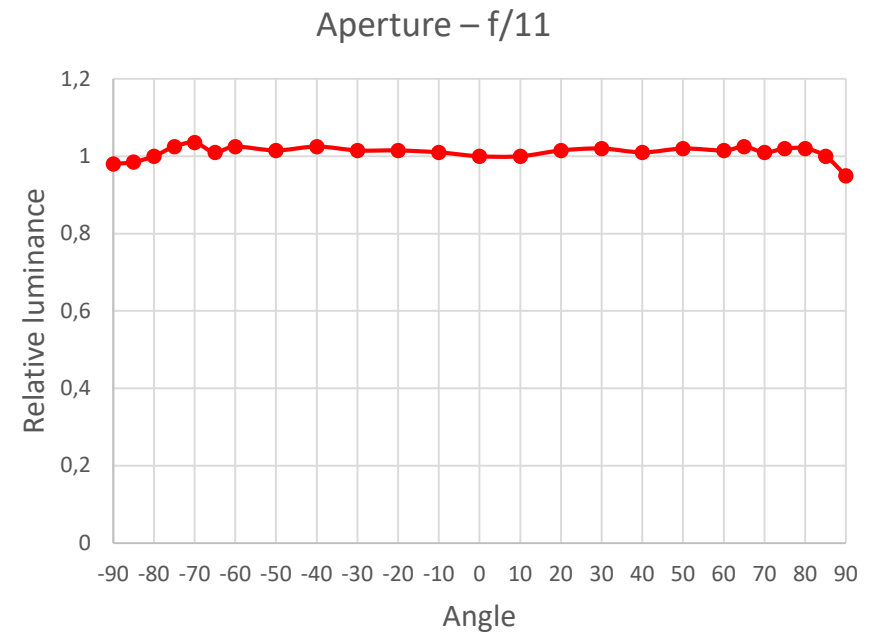
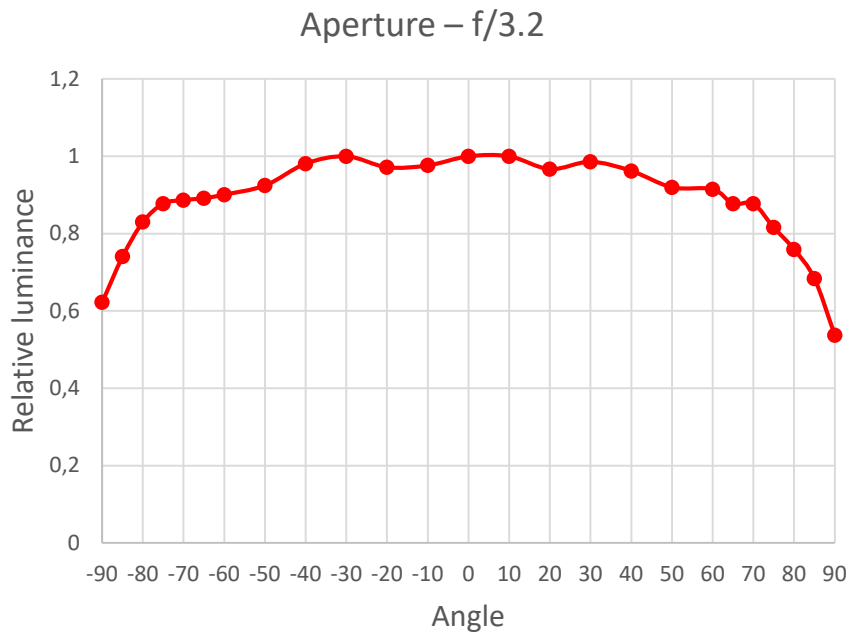


# Vignetting



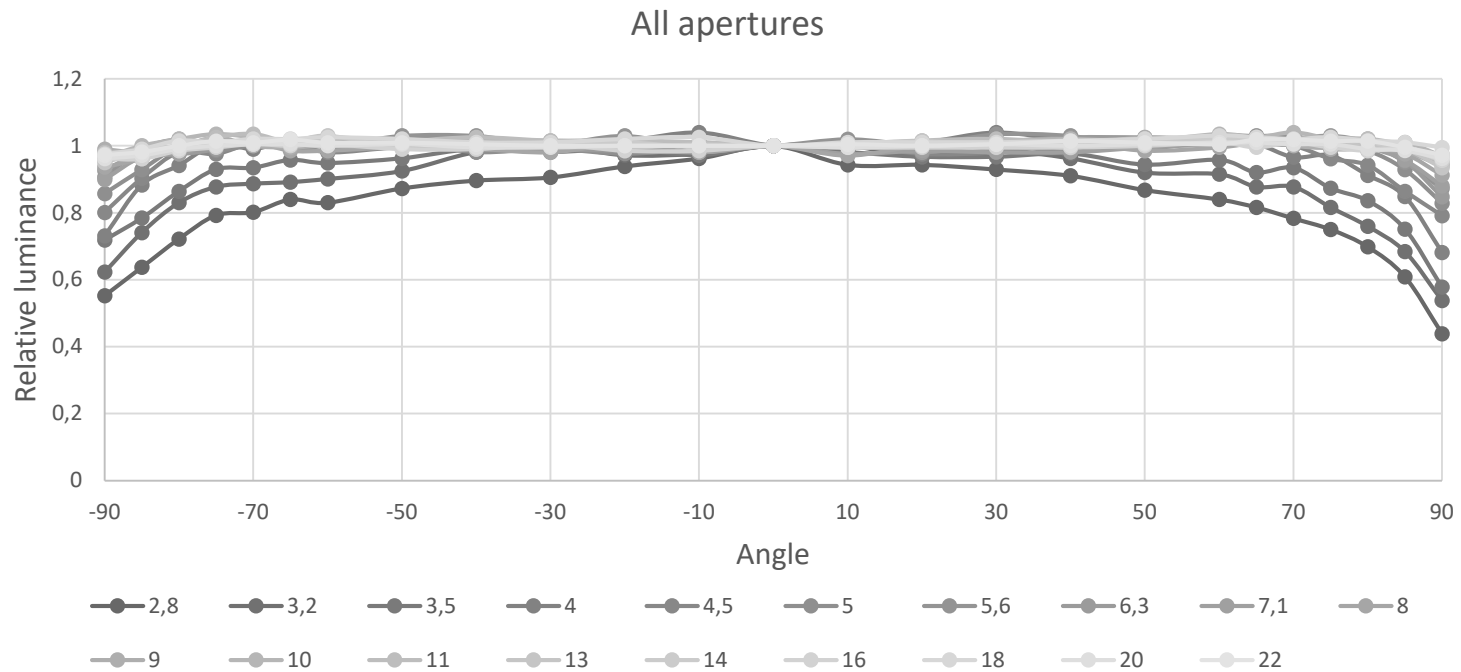
Second setup images curtesy of Clotilde Pierson

# Vignetting



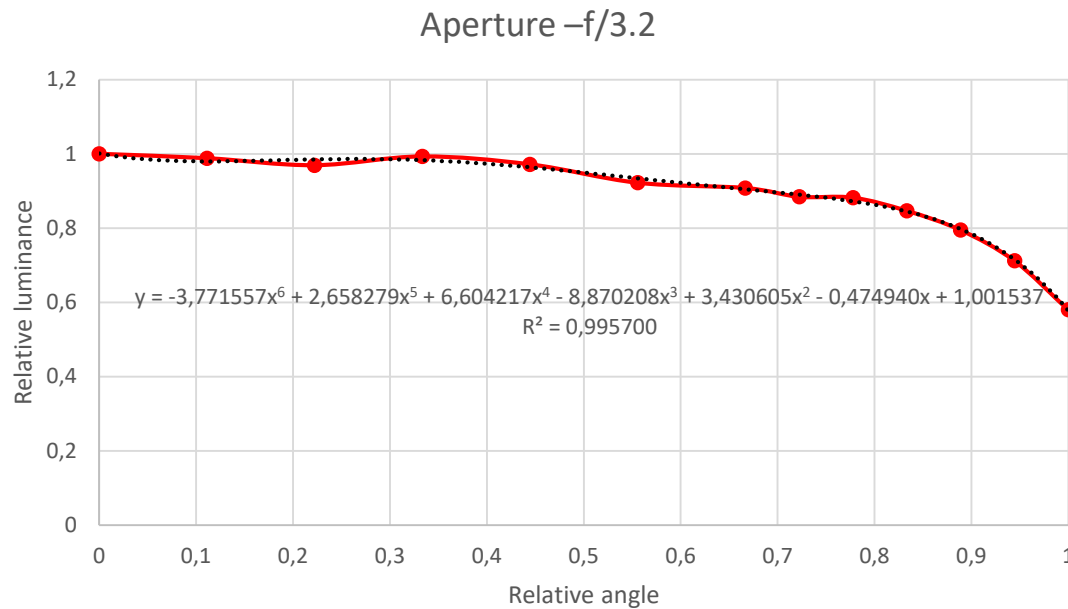
Normalized to lens center

# Vignetting



# Vignetting

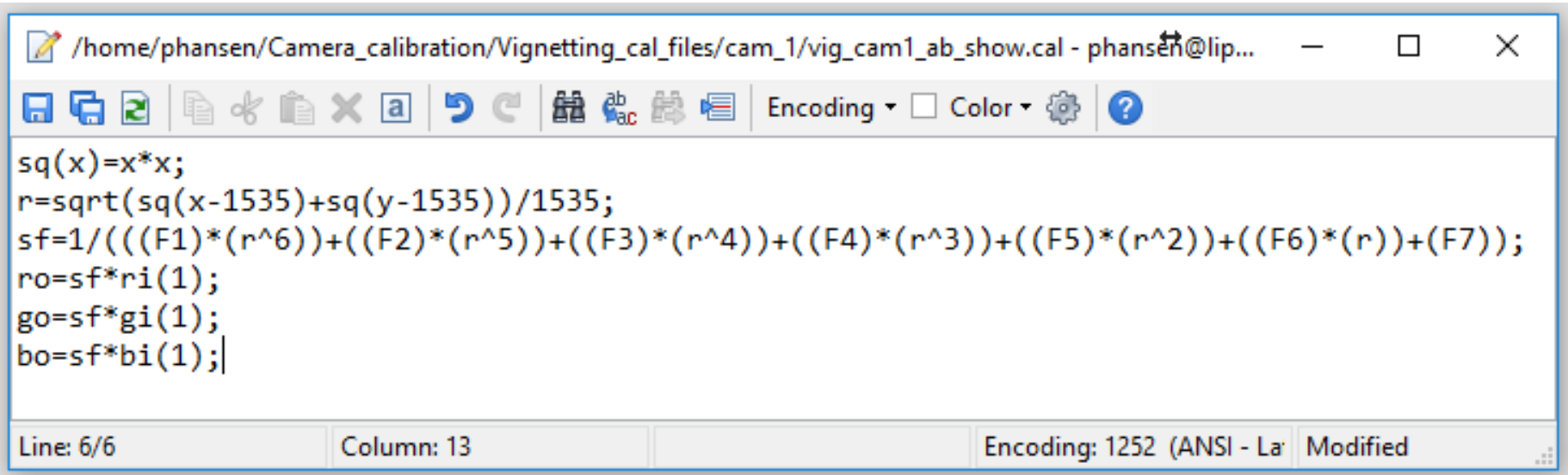
Establish 6<sup>th</sup> order polynomial for vignetting curve



Create a .cal file with the polynomial equation

# Vignetting

Cal file example

A screenshot of a text editor window. The title bar shows the file path: /home/phansen/Camera\_calibration/Vignetting\_cal\_files/cam\_1/vig\_cam1\_ab\_show.cal - phansen@lip... The editor has a toolbar with various icons for file operations and editing. The main text area contains a series of mathematical expressions for a vignetting calibration. The status bar at the bottom indicates the current position: Line: 6/6, Column: 13, and the encoding: 1252 (ANSI - La... Modified.

```
sq(x)=x*x;  
r=sqrt(sq(x-1535)+sq(y-1535))/1535;  
sf=1/(((F1)*(r^6))+((F2)*(r^5))+((F3)*(r^4))+((F4)*(r^3))+((F5)*(r^2))+((F6)*(r))+(F7));  
ro=sf*ri(1);  
go=sf*gi(1);  
bo=sf*bi(1);|
```

Apply to images with

```
pcomb -f [path_to/vignetting.cal] -o [original_image.hdr] > [corrected_image.hdr]
```

# Vignetting

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- Canon 70D
- Sigma 4.5mm f/2.8 fisheye lens



# DSLR camera “self/calibration” procedure

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Create LDR images

Create HDR image

Cut images

Calibrate for vignetting

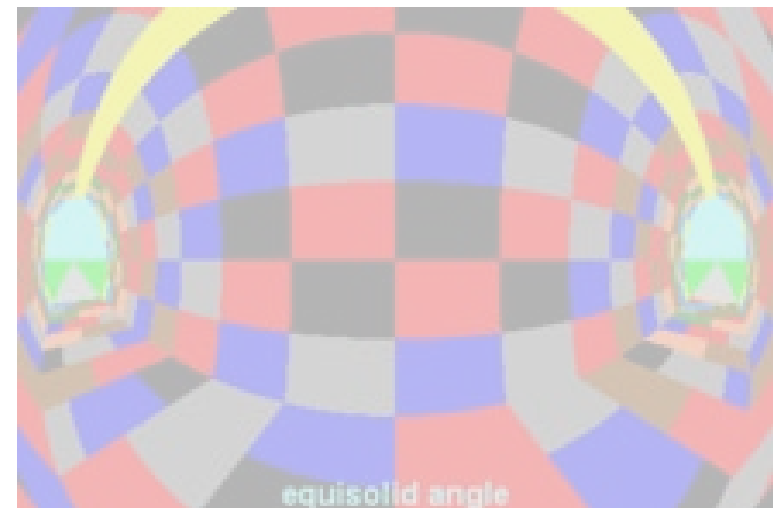
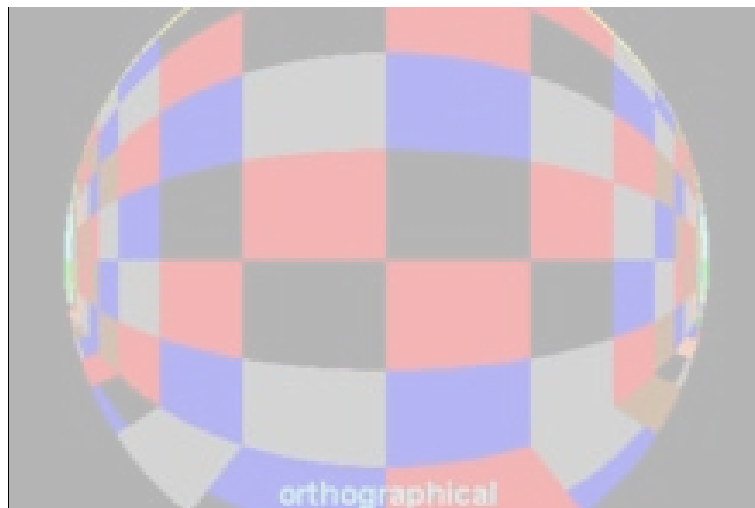
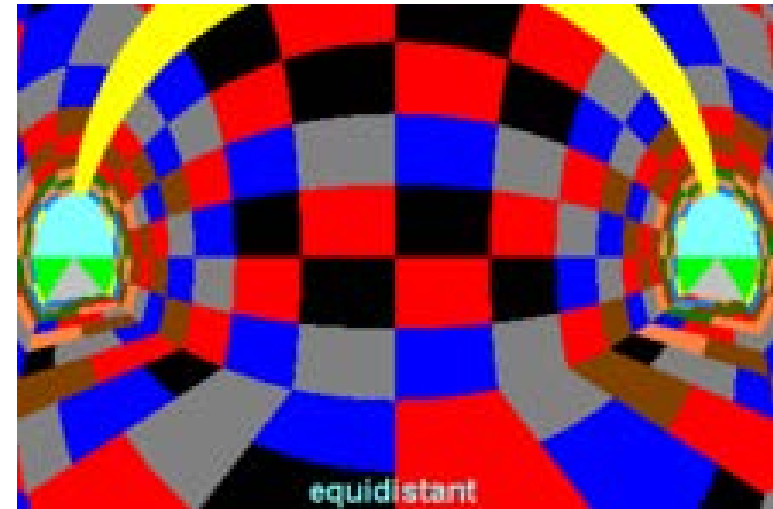
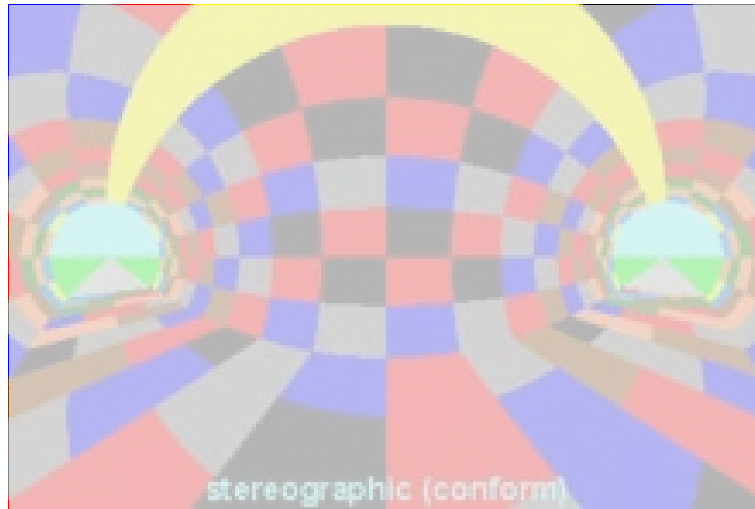
Calibrate for projection

Luminance calibration

Illuminance check

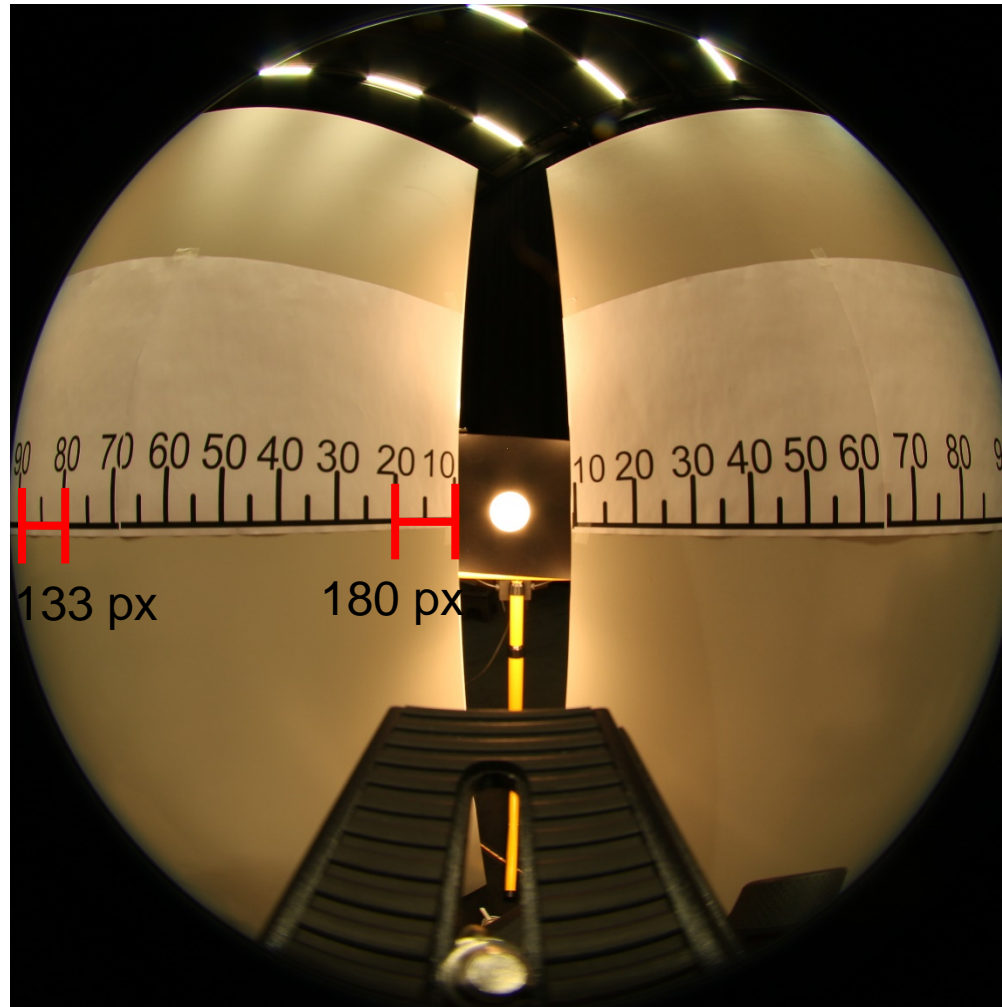


# Projection



# Projection

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# Projection

From Sigma:



## 4.5mm F2.8 EX DC HSM Circular Fisheye EXAGGERATION TO THE MAX

Category: Fisheye Lenses

Typical Photography: Landscape, Wedding & Events, Nature & Wildlife, Specialty

- First circular fisheye designed for APS-C sensors
- 180 degrees angle of view for exaggerated close ups
- Carrying Case, front/rear caps & front adapter ring

Sigma's 4.5mm F2.8 EX DC Circular Fisheye HSM creates an image that is a circular, curved, distorted view of reality when used on a digital SLR camera. One of the most unusual lenses a photographer can use as it produces a circular image within a black surrounding frame. It is ideal for landscapes and panoramic photography. Because of its equisolid angle projection system, the lens can be used for scientific applications. The minimum focusing distance of 5.3 inches allows the photographer to have fun with placement of subjects extremely near to the camera with distorted backgrounds. SLD (Special Low Dispersion) glass employed for effective compensation of color aberration, Super Multi-Layer lens coating reduces flare and ghosting and assures high image quality throughout the entire focal range. In the hands of a photographer looking for creative expression and the opportunity to explore and create, this is the ultimate creative tool. The results are captivating

# Projection

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Fisheye correction file from:

<https://www.radiance-online.org/cgi-bin/viewcvs.cgi/ray/src/cal/cal/>



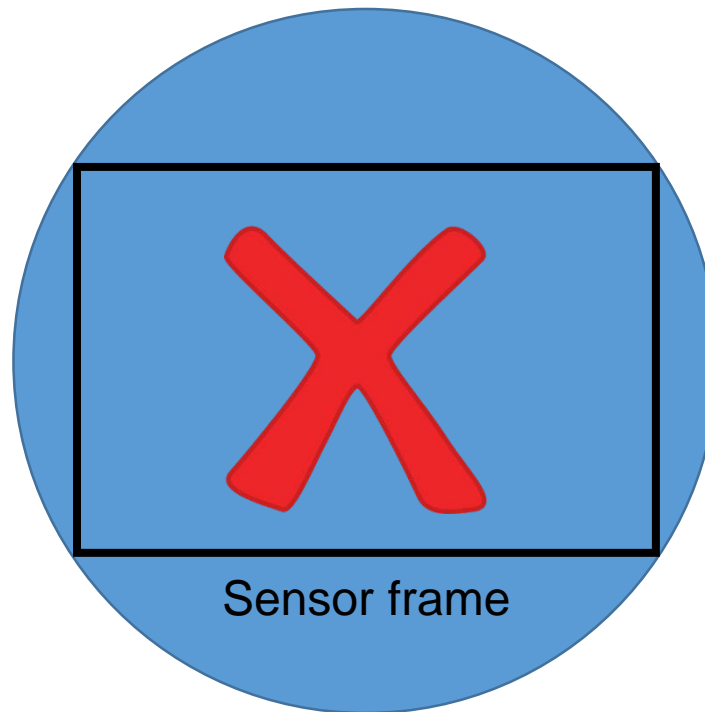
fisheye\_corr.cal

```
pcomb -f [path_to/fisheye_corr.cal] -o  
[original_image.hdr] > [corrected_image.hdr]
```

# Projection

---

Also make sure the fisheye lens fits the sensor frame

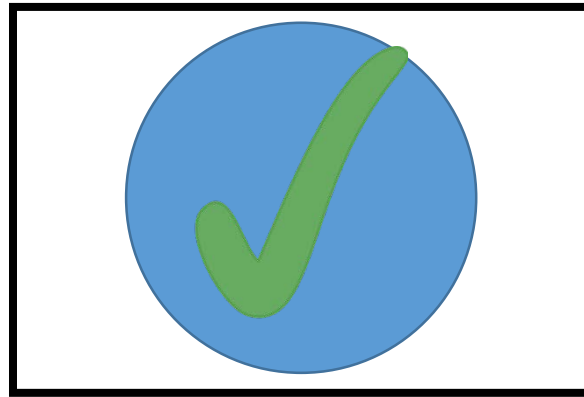


Sensor frame

# Projection

---

Also make sure the fisheye lens fits the sensor frame



Sensor frame

# DSLR camera “self/calibration” procedure

---

Create LDR images

Create HDR image

Cut images

Calibrate for vignetting

Calibrate for projection

Luminance calibration

Illuminance check

# Luminance adjustment



Target	Konica	Image	Factor
1	151	140,2	1,077
2	268	247,2	1,084
3	107	98,5	1,086

```
pcomb -s 1.08 -o [original_image.hdr] > [adjusted_image.hdr]
```

Should be less than  $\pm 20 \%$



# Luminance adjustment



Target	Konica	Image	Factor
1	151	151,1	0,999
2	268	266,2	1,007
3	107	107,8	0,993

```
pcomb -s 1.08 -o [original_image.hdr] > [adjusted_image.hdr]
```

Should be less than  $\pm 20 \%$

# Check header

---

Remove or reset exposure to 1

Set “View” string to the right values (no “tab” in front)

`-vta -vh 180 -vv 180`

Remember to use the current version of Radiance (5.1 at the moment)

```
Lmk_corred_cam_1_ab_11.hdr:
  #?RADIANCE
  CAPDATE= 2017:06:29 11:37:53
  GMT= 2017:06:29 09:37:53
  cam_1_ab_11.hdr:
    CAPDATE= 2017:06:14 09:26:01
    GMT= 2017:06:14 07:26:01
    <stdin>:
      CAPDATE= 2017:06:14 09:26:01
      GMT= 2017:06:14 07:26:01
      <stdin>:
        CAPDATE= 2017:06:14 09:26:01
        GMT= 2017:06:14 07:26:01
        pcompos -x 3070 -y 3070 -h unmodified.hdr -l201 -278
        pcomb -i /home/phansen/Camera_calibration/Vignetting_cal_files/fisheye_corr.cal -o -
        VIEW= -vta -vh 180 -vv 180
        pcomb -f /home/phansen/Camera_calibration/Vignetting_cal_files/cam_1/vig_caml_ab_11.cal -o -
        pcomb -s 1.07298 -o cam_1_ab_11.hdr
        FORMAT=32-bit_rle_rgbe
```

# DSLR camera “self/calibration” procedure

---

Create LDR images

Create HDR image

Cut images

Calibrate for vignetting

Calibrate for projection

Luminance calibration

Illuminance check

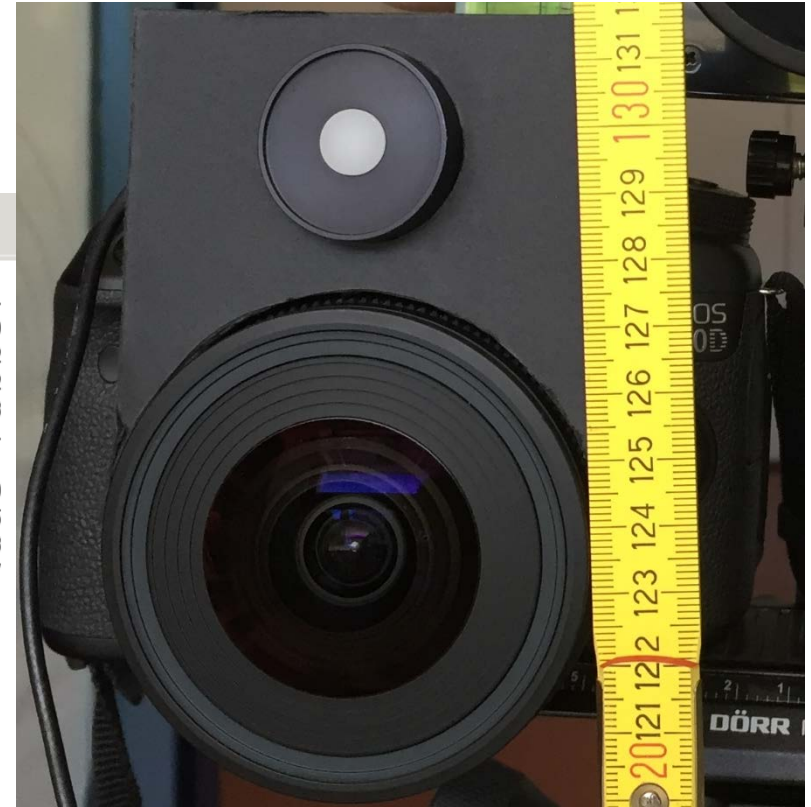
# Illuminance check

Measure illuminance in scene

Calculate from HDR image

Lmk_corr'd_eval_clean					
	No_pixels	x-pos	y-pos	L_s	Omega_s
11	146273.000000	548.138720	769.993411	3357.884426	0.1127824894
1	3.000000	279.000336	1110.000000	1999.802020	0.0000022629
2	2.000000	443.000000	1273.500025	2011.721328	0.0000016632
3	412.000000	1082.261677	1491.465030	2196.412373	0.0004160032
4	8359.000000	1157.213786	1884.209079	5513.991263	0.0083511873
5	16675.000000	1271.252523	2701.581125	2160.390304	0.0133116894
6	33.000000	1235.044517	170.280991	1894.201050	0.0000239151
7	13191.000000	1329.322421	1280.083440	4493.945960	0.0135398500
8	351.000000	1459.133435	2201.706501	2706.522290	0.0003393716
9	14.000000	1689.714460	160.787383	2331.739558	0.0000102313
10	87.000000	2493.705817	1653.963323	2256.372362	0.0000768987
dgp	av_lum	E_v	lum_backg	E_v_dir	dgi
0.240698	372.554743	1145.877970	297.405506	211.175223	15.281463

LMT	Image	Factor
1150	1145,8	1,004



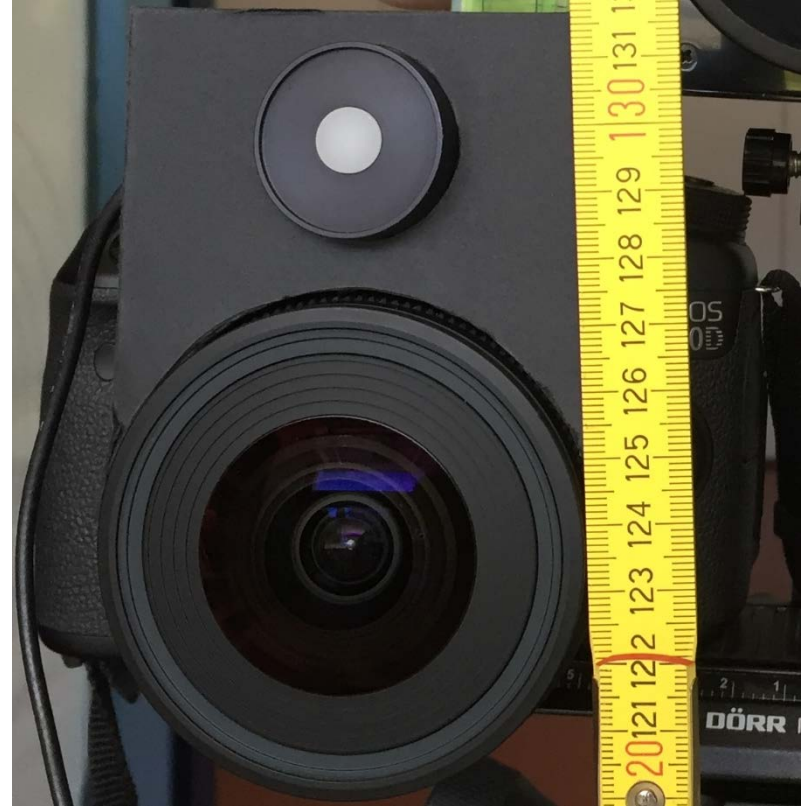
# Illuminance check

---

Do **NOT** use this to adjust luminance

This is a check that the “energy balance” of the image is correct

$\pm 10 \%$  is okay but should be random



# High luminance scenes

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## High luminance scenes

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Be careful - long exposures with very high luminance can “burn out” the image sensor





## High luminance scenes

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Use filters to reduce light on sensor





## High luminance scenes

However, filters raises other problems



Grainy HDR



30 sec exposure at f/11

# High luminance scenes

---

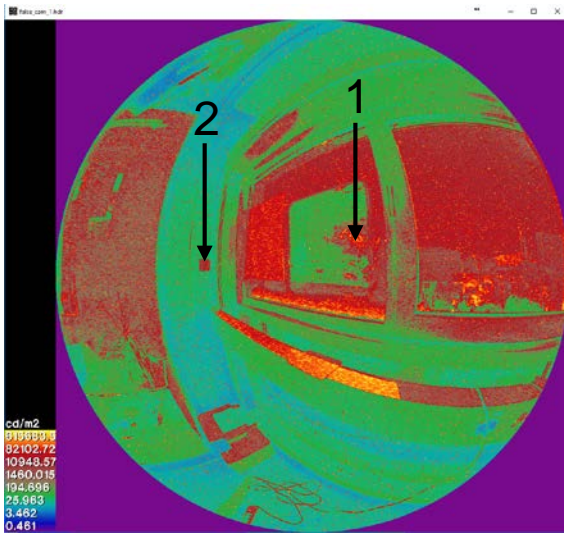
6 layers of 0,3 filters on window



## High luminance scenes

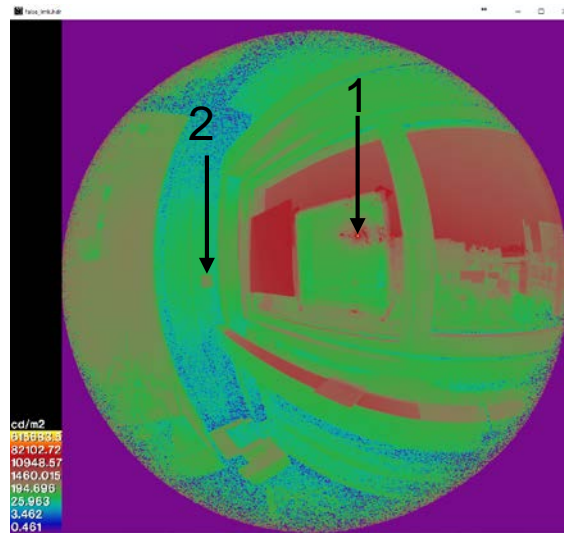
6 layers of 0,3 filters on window

Canon 0.1 % filter



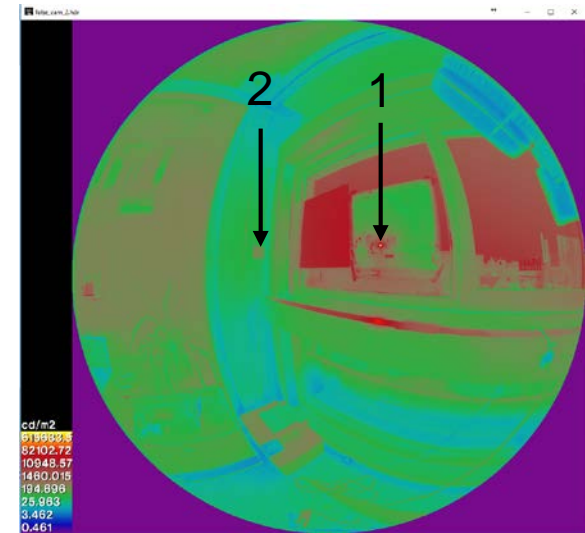
1: 762.973 cd/m<sup>2</sup>  
2: 12.110 cd/m<sup>2</sup>

TechnoTeam 0.01 % filter



1: 1.651.000 cd/m<sup>2</sup>  
2: 274 cd/m<sup>2</sup>

Canon no filter



1: 2.653.980 cd/m<sup>2</sup>  
2: 281 cd/m<sup>2</sup>

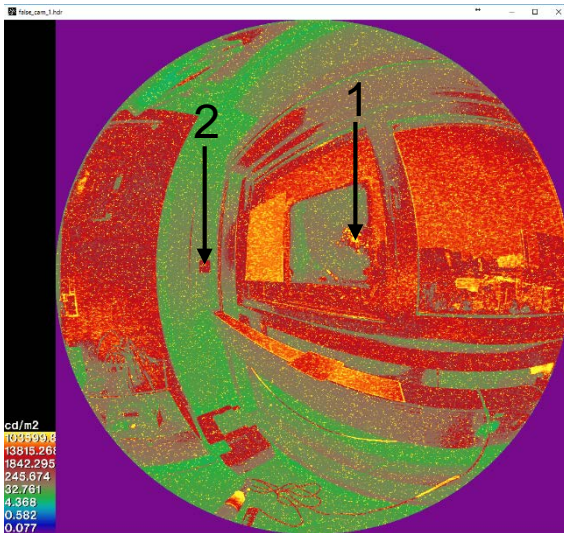
Konica Minolta: 1: 1.674.000 cd/m<sup>2</sup>  
2: 275 cd/m<sup>2</sup>



## High luminance scenes

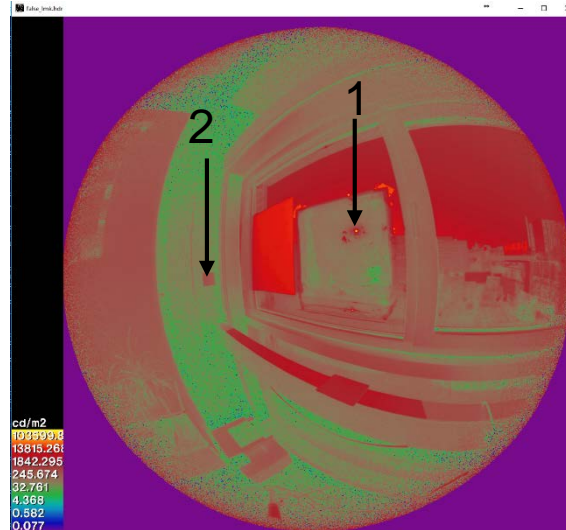
8 layers of 0,3 filters on window

Canon 0.1 % filter



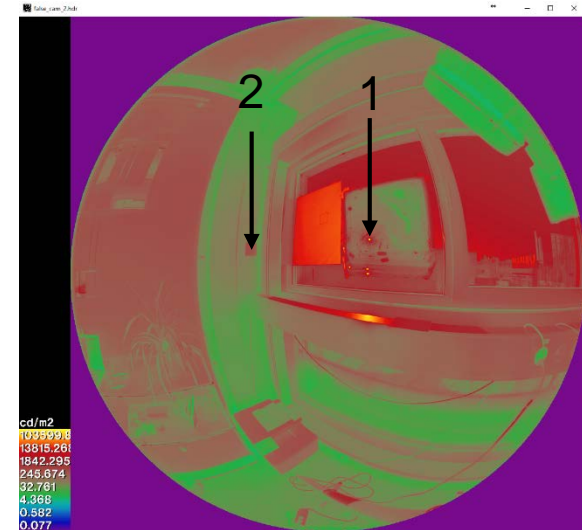
1: 342.192  $\text{cd/m}^2$   
2: 28.125  $\text{cd/m}^2$

TechnoTeam 0.01 % filter



1: 264.000  $\text{cd/m}^2$   
2: 327  $\text{cd/m}^2$

Canon no filter



1: 388.479  $\text{cd/m}^2$   
2: 350  $\text{cd/m}^2$

Konica Minolta: 1: 261.000  $\text{cd/m}^2$   
2: 313  $\text{cd/m}^2$

## High luminance scenes

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Avoid very high luminances

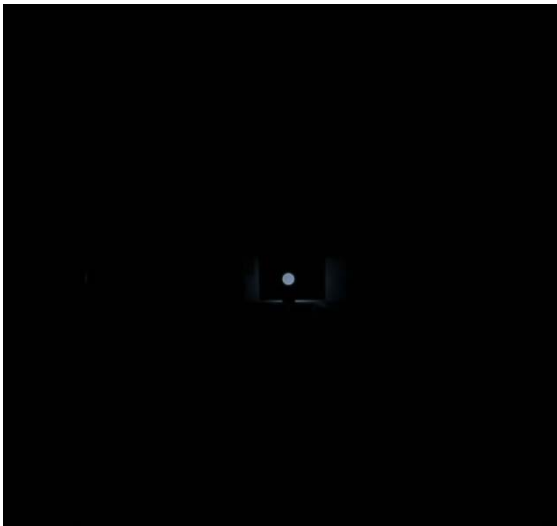
Check that the recorded values are correct

## Other

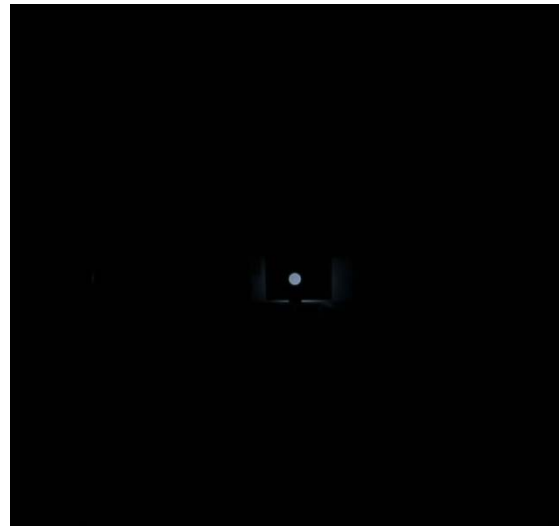
---

### Avoid flicker

- Influences pixel values



R: 159  
G: 181  
B: 203



R: 148  
G: 162  
B: 189

# Synthesis

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## When “self-calibrating”

- Use recommended camera settings
- Use a tripod
- Create good response curves
- Correct for vignetting
- Correct for projection
- Luminance adjust
- Check vertical illuminance
- Check the header
- Be careful with very high luminance

Use the forums; Radiance HDRI is a good start

<https://www.radiance-online.org/community/mailing-lists>